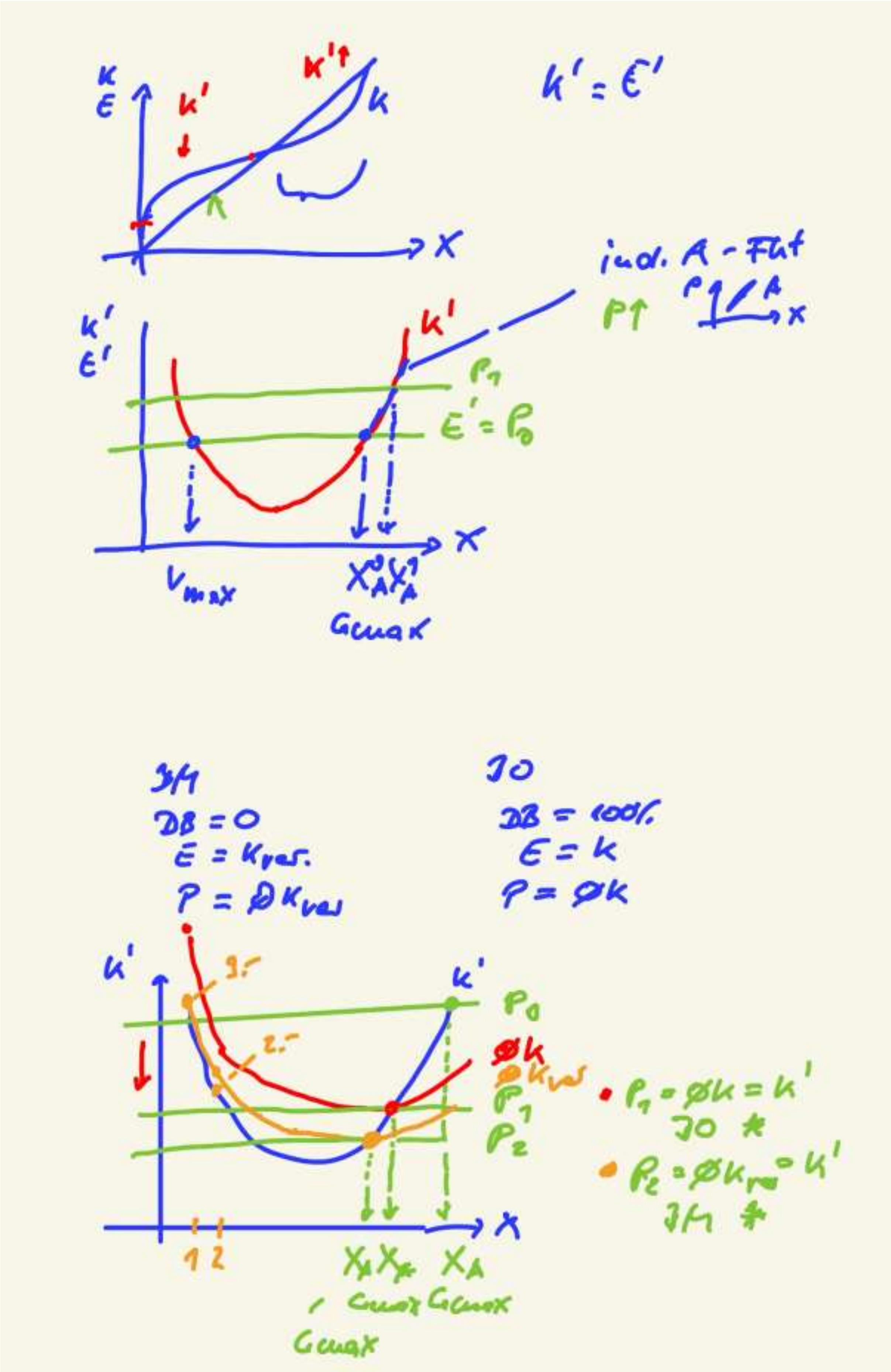
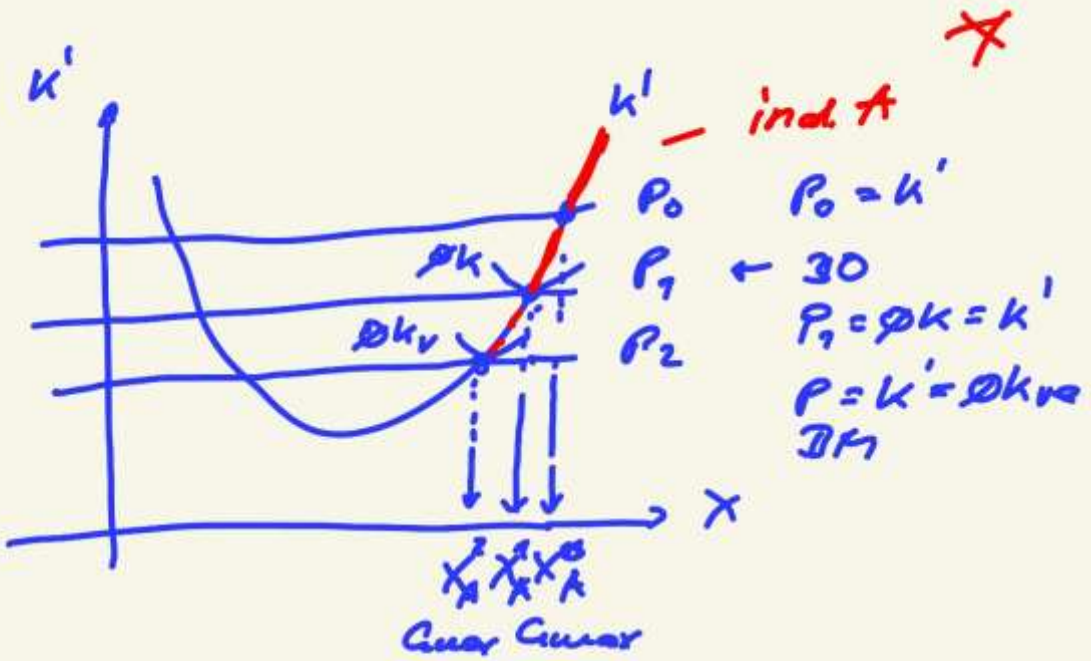
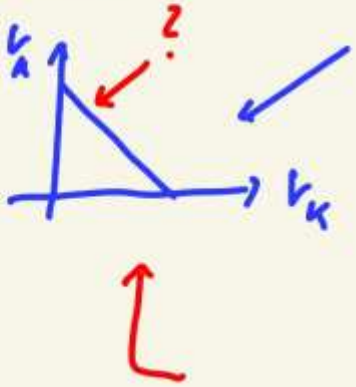
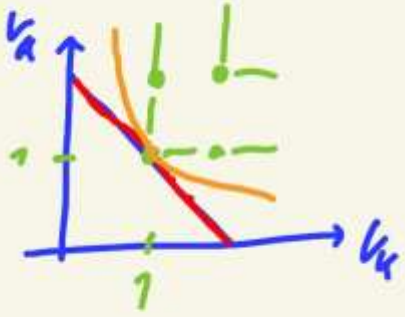

K
E
K'
K'↑
K
X
k' = E'
ind. A - Fkt
P↑
K'
E'
P1
E' = P0
X
Vmax
Gmax
JM
DB = 0
E = Kvar.
P = ØKvar
JO
DB = 100%
E = K
P = ØK
K'
1.-
2.-
P0
ØK
ØKvar
P1
P2
P1 = ØK = K'
JO
P2 = ØKvar = K'
JM
X
1 2
Gmax
Gmax
Gmax



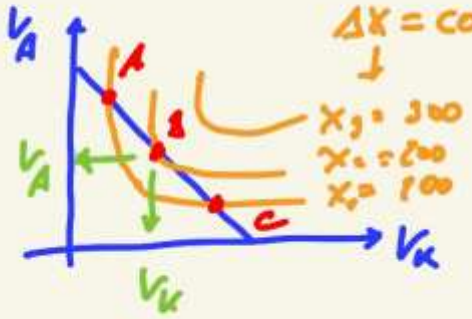
2 variable PF: v_A und v_K



Isokostenpunkte
$k = \text{const}$
$k = v_A \cdot q_A + v_K \cdot q_K$
? Suche $[v_A; v_K]$ mit x_{max}
Isoquanten
a) substitutionale PF
b) limitationale PF



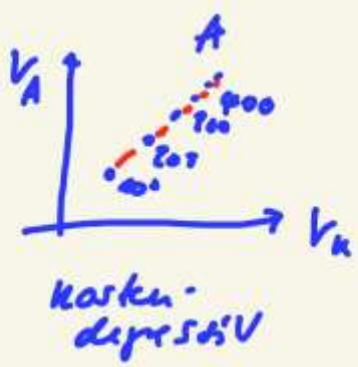
a) substitutive PF
Isoquante
b) limitationale PF
c) realist. Isoquante



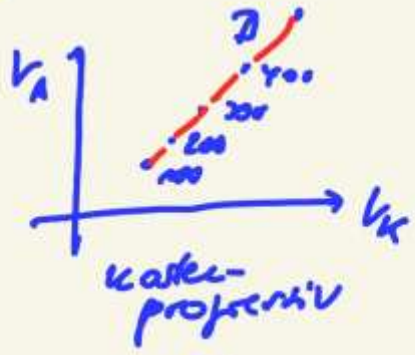
$k(A) = k(B) = k(C)$
$x(A) < x(B) > x(C)$
Optimum

$[v_A; v_K]$ best. x mit k und MKK

* Expansionspfade –
Verh. von MKK
Δx = const



kostendegressiv



kostenprogressiv